



Broadband Noise Predictions Based on a New Aeroacoustic Formulation

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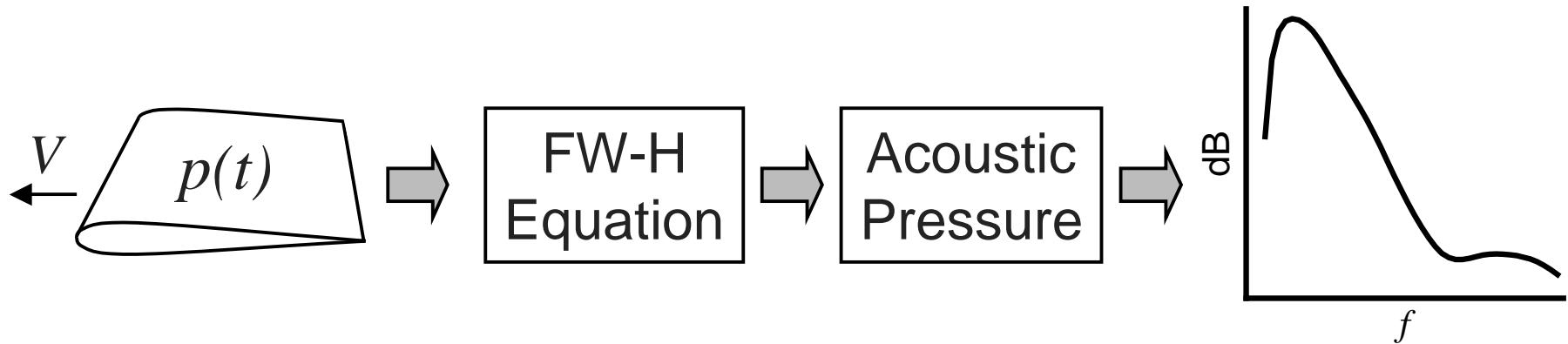
Outline

- Introduction / Motivation
- Acoustic Formulation
- Model Problems
 - Surface Pressure from Thin Airfoil Theory
 - Velocity Scaling Properties, Directivity
- Broadband Noise Prediction
 - Incident Turbulence Noise
 - Comparison with Experiment
 - (Paterson and Amiet, 1976)



Introduction / Motivation

- Broadband Noise Prediction Tools
 - Airframe noise, ducted fan noise
 - Incident turbulence, TE noise
- Time Domain Approach
 - Acoustic Analogy
 - Ffowcs Williams – Hawkings equation
 - Decouples aerodynamics from acoustics
 - Input from CFD or experiment





Acoustic Formulation

$\tilde{f} \geq 0$: surface geometry

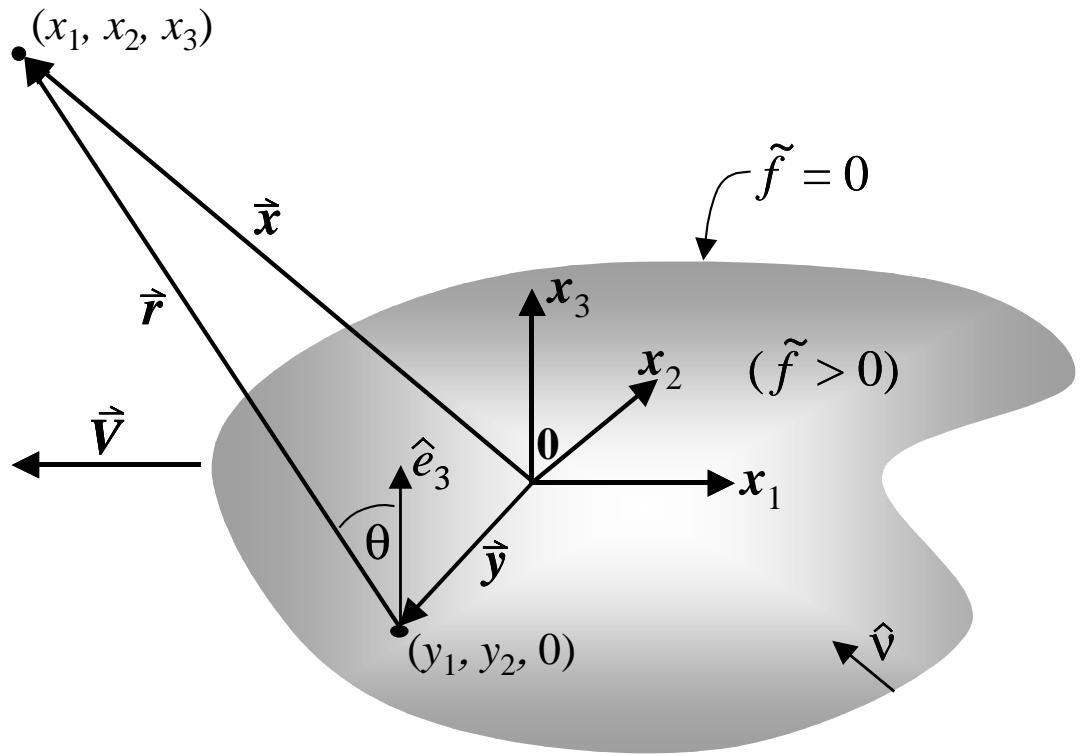
\hat{v} = geodesic normal

\vec{x} = observer position

\vec{y} = source position

$$\vec{r} = \vec{x} - \vec{y}$$

$$\cos \theta = \vec{r} \cdot \hat{\vec{e}}_3 / r$$



The only restriction on the velocity vector is that it lie in the same plane as the surface.

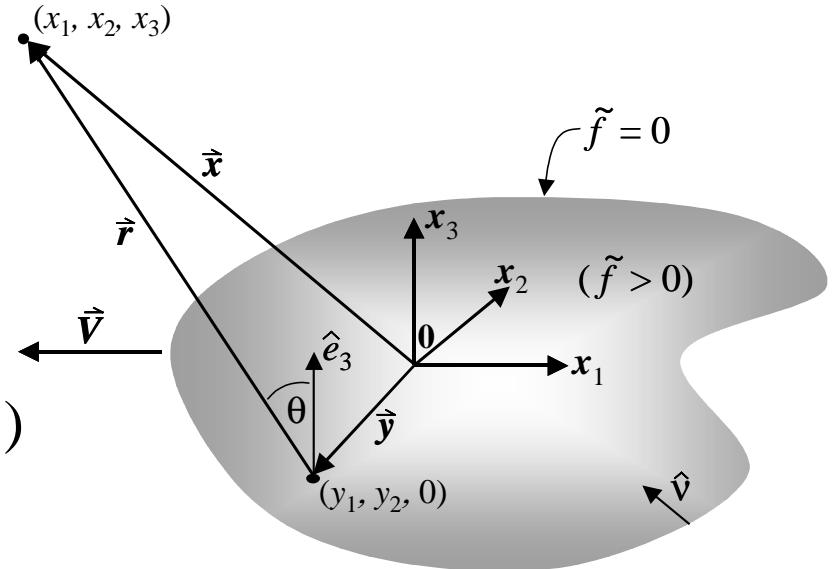


Acoustic Formulation

Ffowcs Williams - Hawkings Equation

Loading Noise (Dipole)

$$\frac{1}{c_0^2} \frac{\partial^2 p'}{\partial t^2} - \nabla^2 p' = -\vec{\nabla} \cdot [p \hat{n} H(\tilde{f}) \delta(x_3)] \\ = -p(x_1, x_2, t) H(\tilde{f}) \delta'(x_3)$$



Solution:

$$4\pi p'(\vec{x}, t) = - \int_{-\infty}^t \int_{R^3} \frac{\delta(g)}{r} p(y_1, y_2, \tau) H(\tilde{f}) \delta'(y_3) d\vec{y} d\tau$$

Free-space Green's function: $\frac{\delta(g)}{4\pi r}$, $g = \tau - t + \frac{r}{c_0}$



Formulation 1B

$$4\pi p'(\vec{x}, t) = \int_{\tilde{f}>0} \left[\frac{(\partial p / \partial \tau - V \partial p / \partial s) \cos \theta}{c_0 r (1 - M_r)} \right]_{\text{ret}} dS + \int_{\tilde{f}>0} \left[\frac{p \cos \theta}{r^2 (1 - M_r)} \right]_{\text{ret}} dS - \int_{\tilde{f}=0} \left[\frac{M_v p \cos \theta}{r (1 - M_r)} \right]_{\text{ret}} d\ell$$

- Given $p(\vec{y}, t)$ on the surface, this formula yields the loading noise at an observer \vec{x} at time t .
- For $M \ll 1, r \gg \lambda$, the first integral dominates the signal.
- The contour integral vanishes at the trailing edge if the Kutta condition is satisfied.
- This formulation is valid for a rotating surface.



Formulation 1B

Test Cases

- Velocity Scaling Properties
- Directivity

Analytic Surface Pressure

- Thin Airfoil Theory (Amiet, 1975-6)
- Periodic Gust – Constant Frequency
- Flat Plate in Uniform Rectilinear Motion



Analytic Surface Pressure

Rectangular Surface at Constant Velocity

$$0 \leq x_1 \leq L_C, \quad -b \leq x_2 \leq b$$

$$\vec{V} = [-U, 0, 0]^T$$

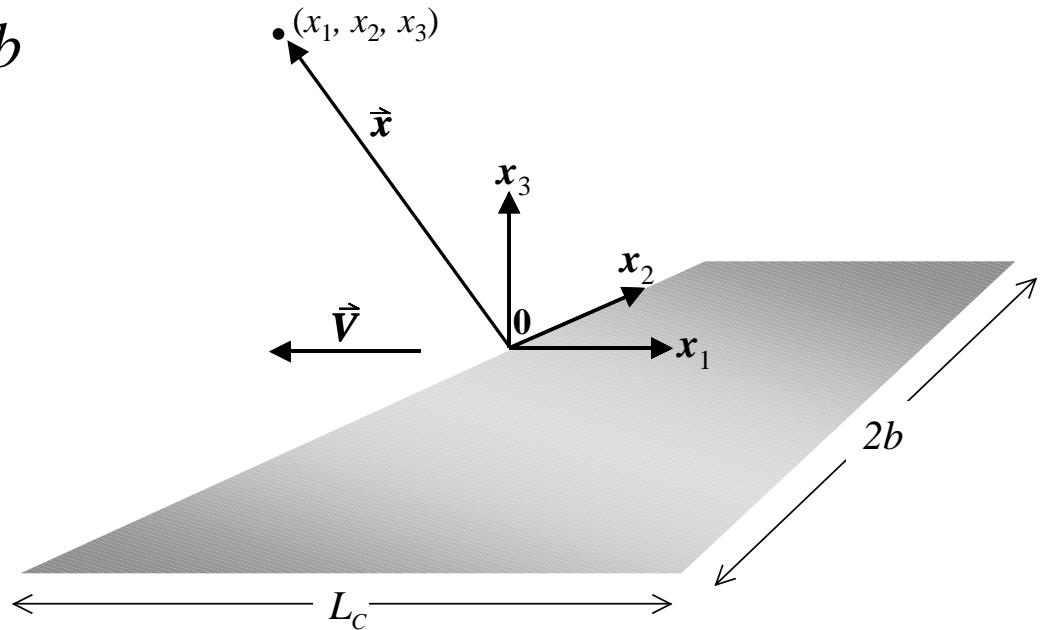
Upwash

$$w(x_1, t) = w_0 e^{-ik(x_1 - Ut)}$$

Surface pressure

$$\Delta P(x_1, t) = \rho_0 U w_0 g(x_1, k) e^{ikUt}$$

$k = \omega/U = \text{constant}, \quad g(x_1, k)$ from thin airfoil theory





Directivity

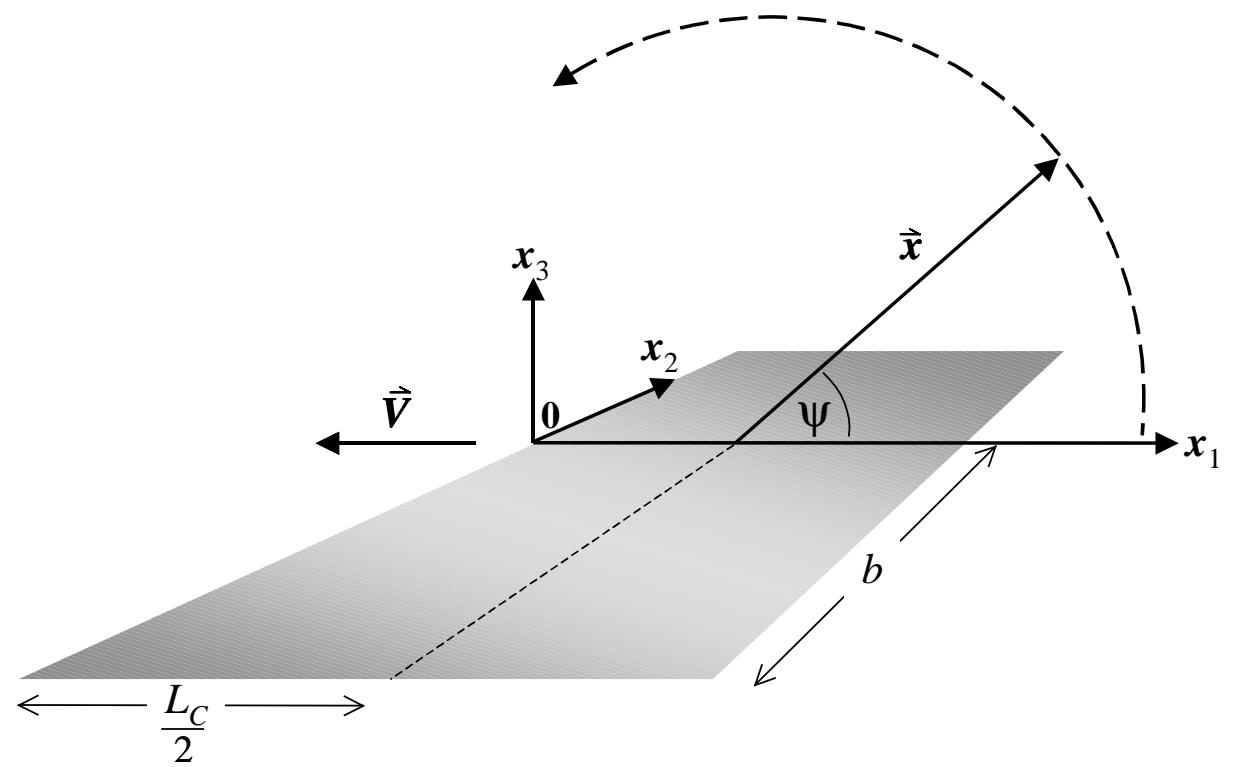
$$L_C = 0.5 \text{ m}$$

$$2b = 2.0 \text{ m}$$

$$M = 0.2$$

$$U = 68.6 \text{ m/s}$$

$$w_0 = 0.05 U$$



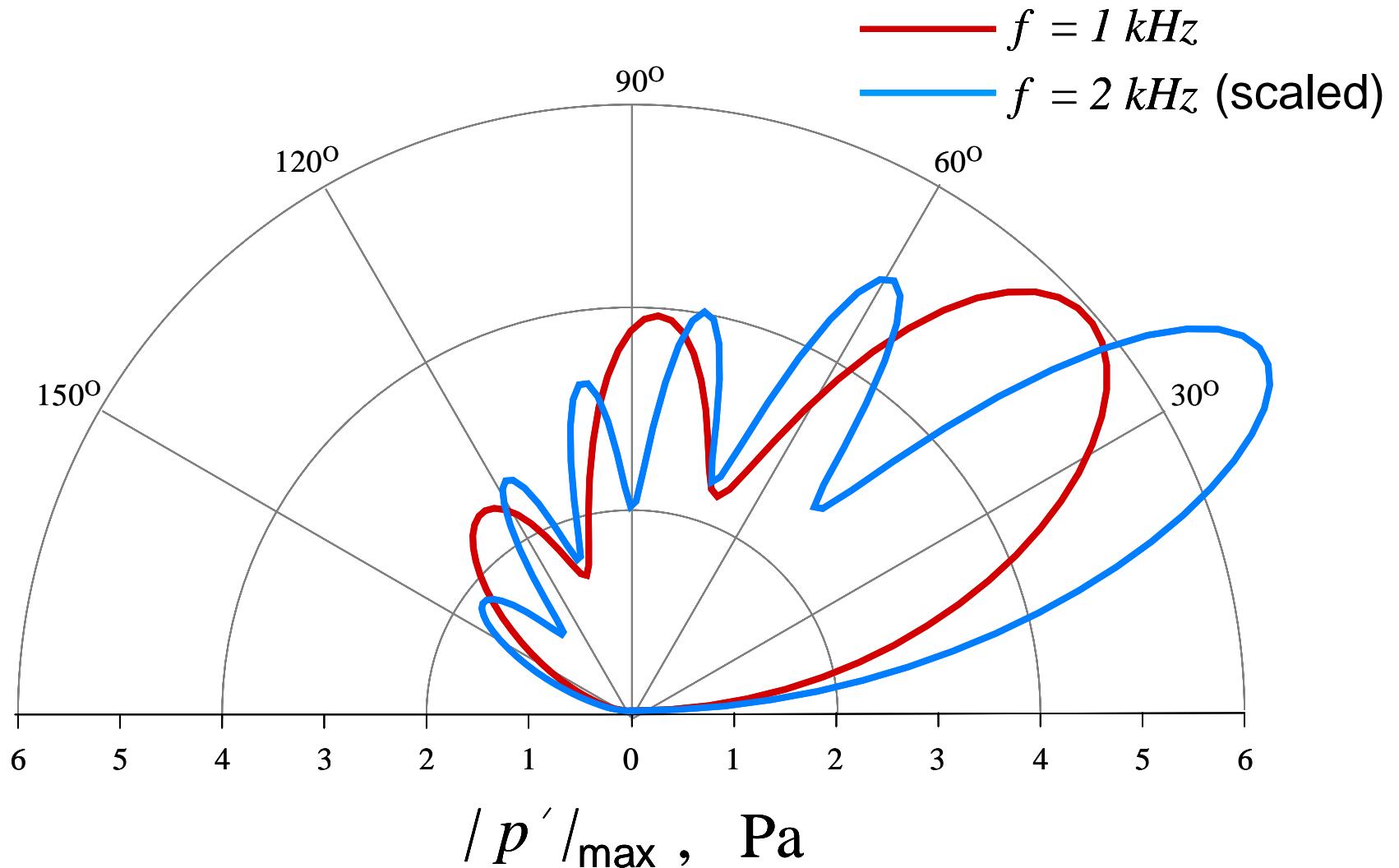
Test Cases

$$\vec{x} : (r, \psi), \ r = 3 \text{ m}, \ 0 \leq \psi \leq \pi$$

$$f_1 = 1 \text{ kHz}, \ f_2 = 2 \text{ kHz}$$



Directivity





Incident Turbulence Noise

Experiment: Paterson and Amiet (1976)

NACA 0012 Airfoil

Chord = 0.23 m

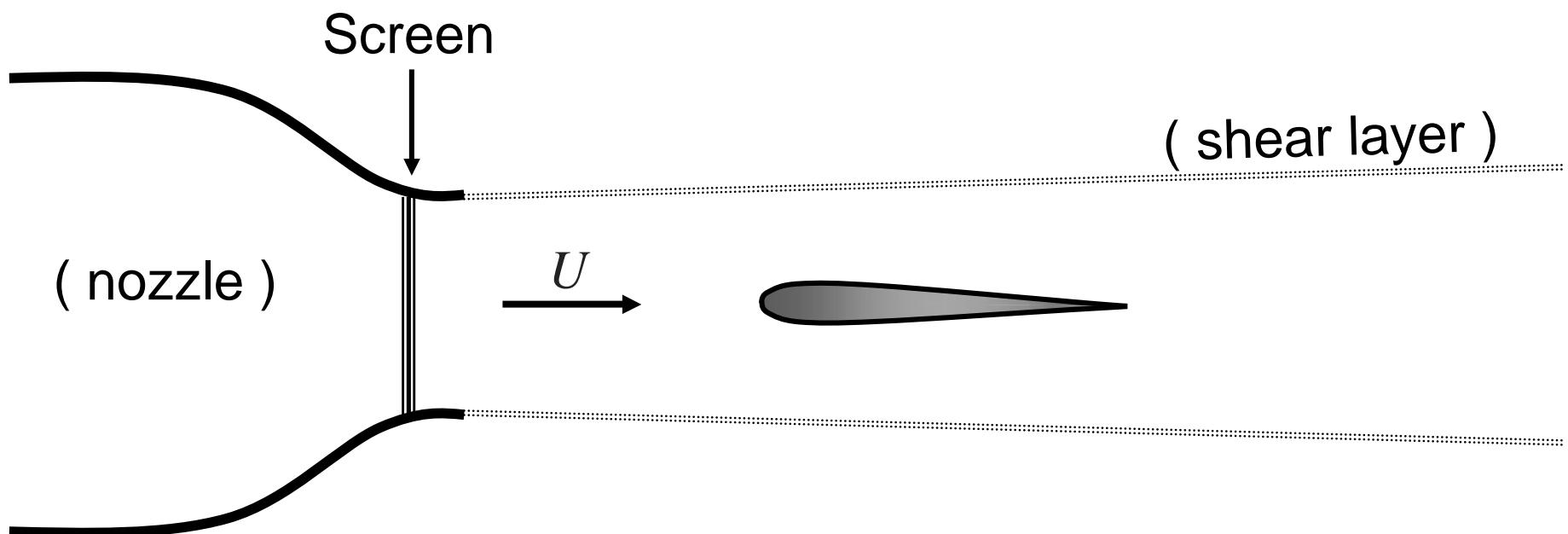
Span = 0.53 m

α = 0 degrees

Microphone:

r = 2.25 m,

θ = 90 degrees





2D Periodic Gust

Upwash

$$w(x_1, x_2, t) = \int_{-\infty}^{\infty} \int_{-\infty}^{\infty} \hat{w}(k_1, k_2) e^{-i[k_1(x_1 - Ut) + k_2 x_2]} dk_1 dk_2$$

Surface pressure

$$\Delta P(x_1, x_2, t) = \rho_0 U \int_{-\infty}^{\infty} \int_{-\infty}^{\infty} \hat{w}(k_1, k_2) g(x_1, k_1, k_2) e^{i(k_1 Ut - k_2 x_2)} dk_1 dk_2$$

Amiet (1975)

Skewed gusts contribute little to the sound received by an observer in the plane $x_2 = 0$ (mid-span), i.e. $k_2 = 0$ is the only spanwise wave number to consider.



Broadband Surface Pressure

$$\Delta P(x_1, t) \approx \rho_0 U \sum_{n=-N}^N A_{n,0} g(x, k_{1,n}, 0) e^{i(k_{1,n} U t + \Phi_n)}$$

$$A_{n,0} = [S_{ww}(k_{1,n}, 0) \Delta k_1 \Delta k_2]^{1/2}$$

$S_{ww}(k_1, k_2)$ = power spectral density of w

Φ_n = random phase angle on $[0, 2\pi]$

Without explicit spanwise integration, this formulation can be expected to require amplitude scaling in the far field, but the spectral shape of the noise will be unaffected.



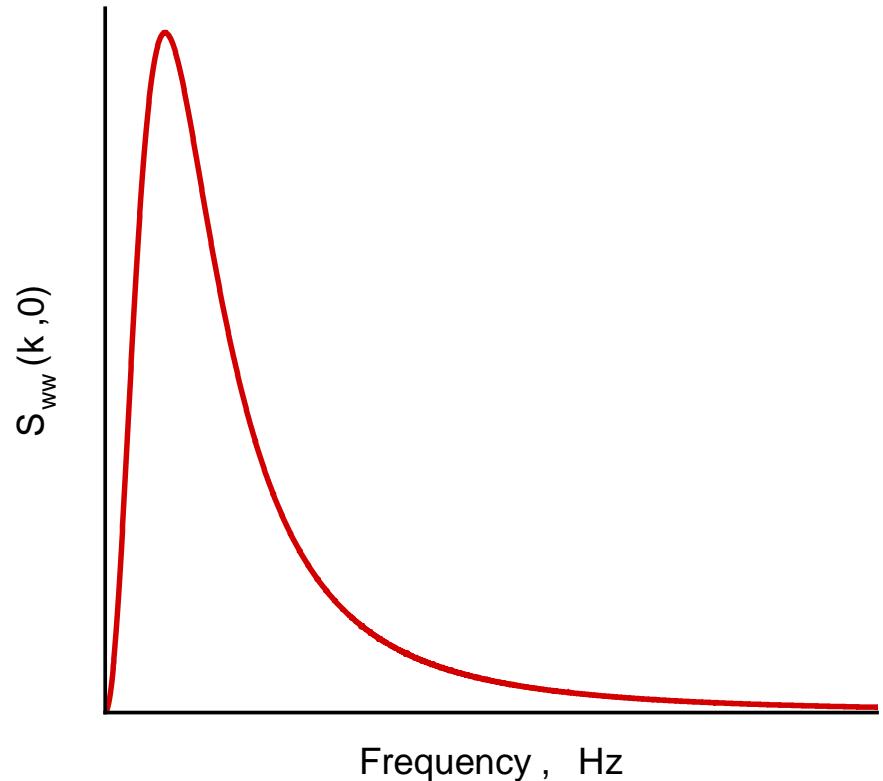
Turbulence PSD

2-Component von Karman Formula

$$S_{ww}(k_1, k_2) = \frac{4}{9\pi} \frac{u^2}{k_e^2} \frac{\hat{k}_1^2 + \hat{k}_2^2}{\left[1 + \hat{k}_1^2 + \hat{k}_2^2\right]^{7/3}}$$

$$\hat{k}_i = \frac{k_i}{k_e}, \quad k_e = \frac{\sqrt{\pi}}{L_1} \frac{\Gamma(5/6)}{\Gamma(1/3)}$$

L_1 and u^2 determined by experimental measurement

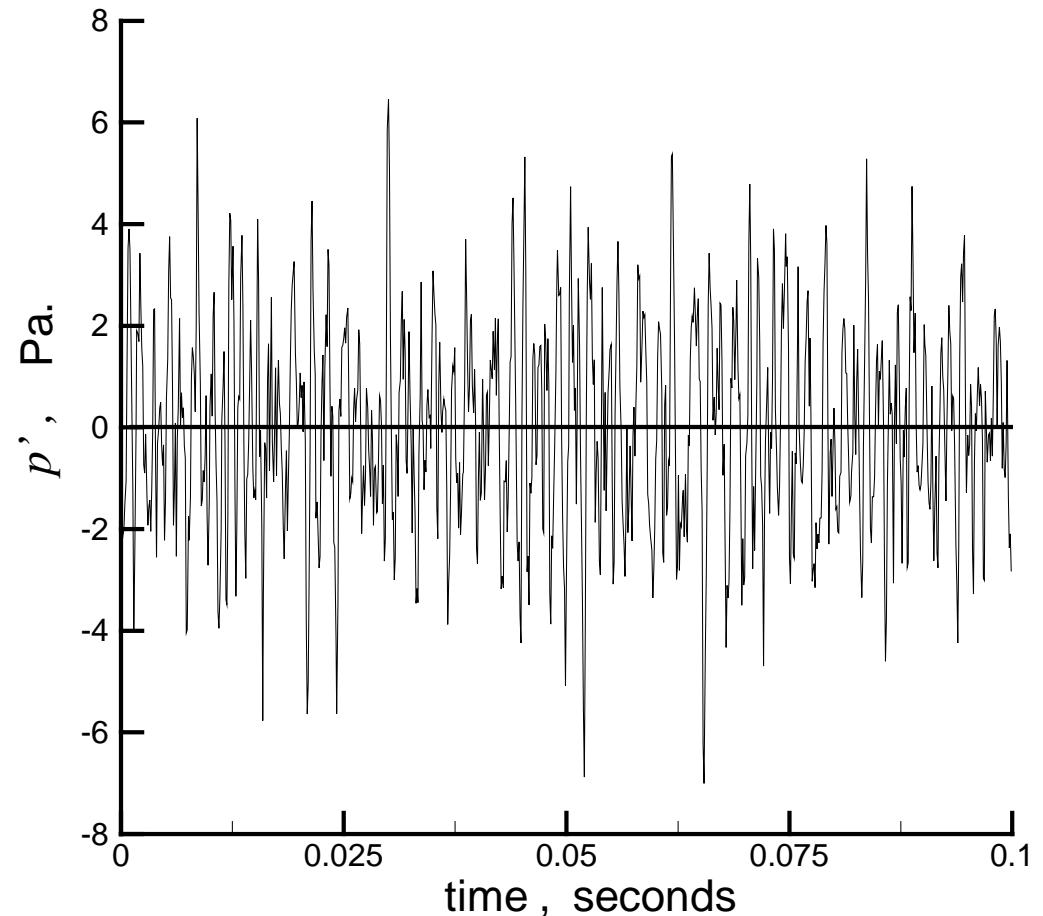




Broadband Prediction in Time

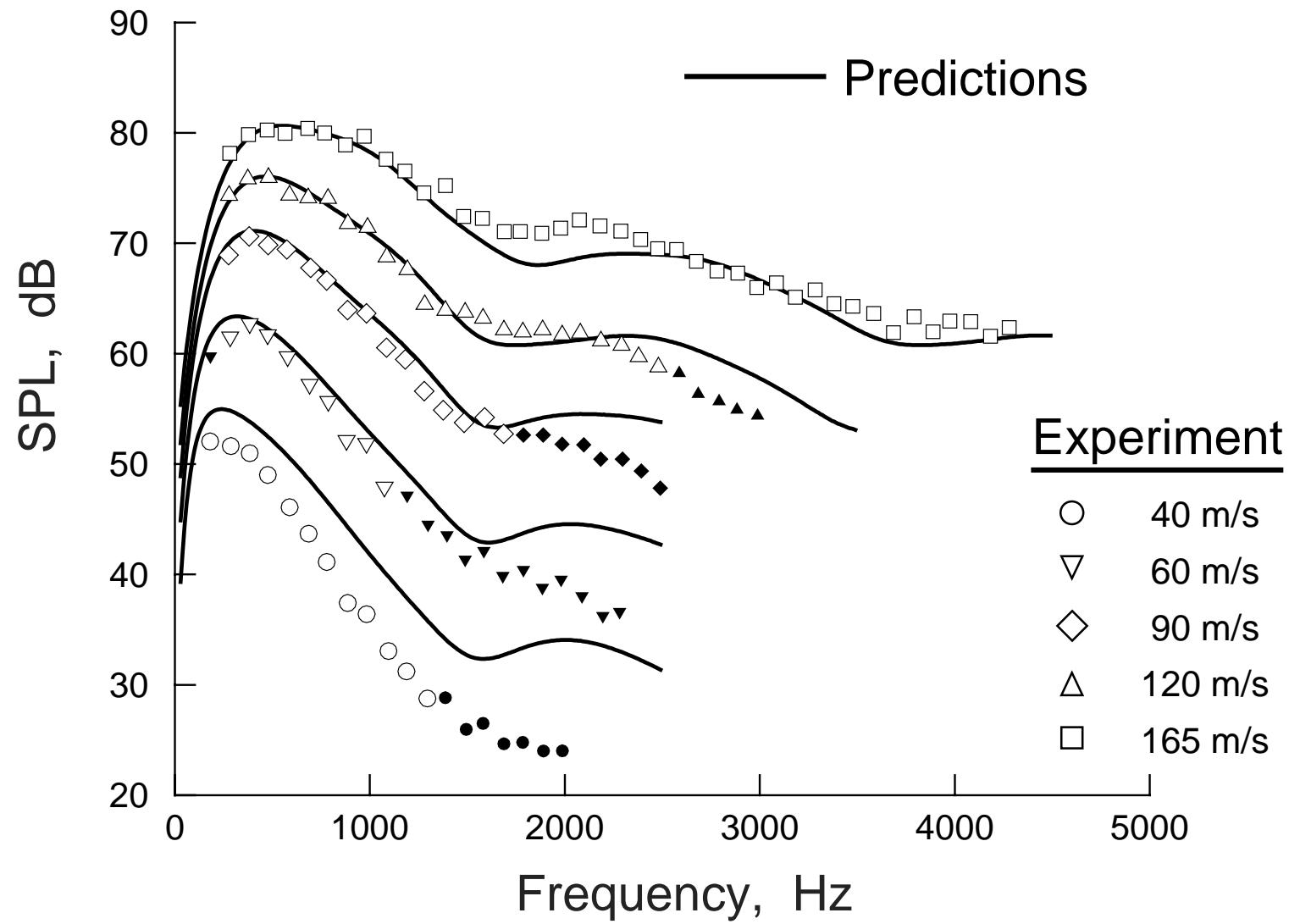
- Surface pressure input to Formulation 1B
- Five tunnel speeds:
 $U = 40, 60, 90, 120, 165 \text{ m/s}$
- Directivity and amplitude corrected for refraction through shear layer
- Acoustic pressure Fourier analyzed to convert to spectral density

Predicted Signal
 $U = 165 \text{ m/s}$





Far Field Noise Spectrum





Concluding Remarks

- A new solution to the FW-H equation provides a useful formulation for loading noise predictions.
- Although simple in form, Formulation 1B is applicable to rotating surfaces.
- A broadband noise prediction was shown to agree well with experimental measurement.
- The formulation's simplicity lends itself well to statistical analysis of broadband noise.
- Future research will include the application of the statistical formulation to trailing edge noise.